

Abstract

An object detection system, in particular for a motor vehicle (2), is described in which the object detection system (20) has multiple object detectors and/or operating modes with which different detection ranges and/or detection zones are detected. In this case, an object detector is preferably a radar sensor which has a relatively large detection range (21) with a relatively small angular detection zone in a first operating mode and has a detection range (22) that is small relative to the first with an enlarged angular detection zone in a second operating mode.

(Fig.)